

# MATH 1AA3/1ZB3 Relevant Theorems

Steward Calculus - Sections 14 & 15

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April 4, 2025

# Clairaut's Theorem

## Clairaut's Theorem (MY ONE TRUE LOVE)

Suppose  $f$  is defined on a disk  $D$  that contains the point  $(a, b)$ . If the function  $f_{xy}$  and  $f_{yx}$  are both continuous on  $D$  then,

$$f_{xy}(a, b) = f_{yx}(a, b)$$

## Why is this helpful?

- Usually they may only give you  $f_{xy}$  or  $f_{yx}$  only.
- Sometimes one is easier to compute than the other.

# Equations 1

## Equation of a Tangent Plane

Suppose  $f$  has continuous partial derivatives. An equation of the tangent plane to the surface  $z = f(x, y)$  at the point  $P(x_0, y_0, z_0)$  is:

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

## Linear Approximation

$$f(x, y) \approx f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

## Total Differential/Differential $dz$

$$dz = f_x(x, y)dx + f_y(x, y)dy$$

## Equations 2

### Chain Rule (Case 1)

Suppose that  $z = f(x, y)$  is a differentiable function of  $x$  and  $y$  where  $x = g(t)$  and  $y = h(t)$  are both differentiable functions of  $t$ . Then,  $z$  is a differentiable function of  $t$  and:

$$\frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

### Chain Rule (Case 2)

Suppose that  $z = f(x, y)$  is a differentiable function of  $x$  and  $y$  where  $x = g(s, t)$  and  $y = h(s, t)$  are differentiable functions of  $s$  and  $t$ . Then,

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s}, \quad \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$$

## Equations 3

### Implicit Differentiation (Case 1)

$$\frac{\partial F}{\partial x} \frac{dx}{dx} + \frac{\partial F}{\partial y} \frac{dy}{dx} = 0 \Rightarrow \frac{dy}{dx} = \frac{-F_x}{F_y}$$

### Implicit Differentiation (Case 2)

$$\frac{\partial F}{\partial x} \frac{\partial x}{\partial x} + \frac{\partial F}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial F}{\partial z} \frac{\partial z}{\partial x} = 0 \Rightarrow \frac{\partial z}{\partial x} = \frac{-F_x}{F_z} \quad \& \quad \frac{\partial z}{\partial y} = \frac{-F_y}{F_z}$$

## Theorem

If  $f$  is a differentiable function of  $x$  and  $y$  then  $f$  has a directional derivative in the direction of any unit vector  $\mathbf{u} = \langle a, b \rangle$  and

$$D_{\mathbf{u}}f(x, y) = f_x(x, y)a + f_y(x, y)b = \nabla f(x, y) \cdot \mathbf{u}$$

If the unit vector  $\mathbf{u}$  makes an angle  $\theta$  with the positive  $x$ -axis then write  $\mathbf{u} = \langle \cos \theta, \sin \theta \rangle$  and we have:

$$D_{\mathbf{u}}f(x, y) = f_x(x, y) \cos \theta + f_y(x, y) \sin \theta$$

### Gradient

If  $f$  is a function of two variables  $x$  and  $y$ , then the gradient of  $f$  is the vector function  $\nabla f$ :

$$\nabla f(x, y) = \frac{\partial f}{\partial x}i + \frac{\partial f}{\partial y}j$$

If you had three variables,  $x, y, z$  then:

$$\nabla f(x, y, z) = \frac{\partial f}{\partial x}i + \frac{\partial f}{\partial y}j + \frac{\partial f}{\partial z}k$$

## Directional Derivatives 3 & More Equations

### Maximum Value of the Directional Derivative

Suppose  $f$  is differentiable. The maximum value of the directional derivative  $D_{\mathbf{u}}f(\mathbf{x})$  is  $|\nabla f(\mathbf{x})|$  and it occurs when  $\mathbf{u}$  has the same direction as  $\nabla f(\mathbf{x})$ .

### Equation of the Tangent Plane

$$F_x(x_0, y_0, z_0)(x - x_0) + F_y(x_0, y_0, z_0)(y - y_0) + F_z(x_0, y_0, z_0)(z - z_0) = 0$$

### Symmetric Equations of the Normal Line

$$\frac{x - x_0}{F_x(x_0, y_0, z_0)} = \frac{y - y_0}{F_y(x_0, y_0, z_0)} = \frac{z - z_0}{F_z(x_0, y_0, z_0)}$$

# Best Theorem for Multiple Integrals

## Fubini's Theorem (MY ACTUAL ONE TRUE LOVE)

If  $f$  is continuous on the rectangle:

$$R = \{(x, y) \mid a \leq x \leq b, c \leq y \leq d\}$$

Then:

$$\int_a^b \int_c^d f(x, y) dy dx = \int_c^d \int_a^b f(x, y) dx dy$$

## Why is this helpful?

- It can be very easy to integrate when you switch sides.
- I've noticed most examples in your practice exam are so much easier if you reversed the order instead of doing it directly.